

AMENDMENT UNDER 37 C.F.R. § 1.116
U.S. APPLN. NO. 09/890,577

AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions and listings of claims in the application:

LISTING OF CLAIMS:

1. (currently amended): Device (10) for manual control of a surgical guide (G), comprising a body (12) provided with a conduit (14) for passage of the surgical guide (G), and a member (16) for axially immobilizing the surgical guide relative to the body, which member (16) comprises a conduit (50) for receiving the surgical guide and is displaceable between a position in which it immobilizes the surgical guide and in which the conduits (14, 50) formed in the body (12) and in the immobilizing member (16) are not aligned, and a position in which it releases the surgical guide and in which the conduits (14, 50) formed in the body (12) and in the immobilizing member (16) are aligned, the device comprising means (44) for elastic return of the immobilizing member (16) to its immobilizing position, characterized in that said immobilizing member (16) is made integral in one molded in one single piece with the body (12).

2. (previously presented): Manual control device according to Claim 1, characterized in that said body (12) comprises a seat (28) for receiving the immobilizing member (16) in the immobilizing position, which seat (28) forms an interruption of the body conduit (14), which body conduit (14) delimits, on each side of the seat (28), two spans (62, 64) for transverse support of the surgical guide (G).

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3. (original): Control device according to Claim 2, characterized in that, at rest, the immobilizing member (16) is outside the seat (28) provided for receiving the immobilizing member.

4. (previously presented): Manual control device according to Claim 3, characterized in that it comprises an arm (18) bearing said immobilizing member (16), which arm (18) is articulated relative to the body (12).

5. (original): Manual control device according to Claim 4, characterized in that the arm (18) bearing the immobilizing member is connected to the body (12) via an elastically deformable connecting region (44) constituting said means for elastic return of the immobilizing member (16) to its immobilizing position.

6. (previously presented): Manual control device according to Claim 1, characterized in that it comprises an arm (18) bearing said immobilizing member (16), which arm (18) is articulated relative to the body (12).